#### CHALLENGES IN NEAR NAVIGATION

B. G. Williams, J. K. Miller, P. G. Antreasian, C. E. Helfrich, W. M. Owen, D. K. Yeomans

Jet Propulsion Laboratory, California Institute of Technology, Pasadena, CA

The Near Earth Asteroid Rendezvous (NEAR) Discovery mission is the first to send a spacecraft to rendezvous with and orbit about an asteroid. Launched in February 1996, the interplanetary trajectory of the NEAR spacecraft included a targeted flyby of the asteroid 253 Mathilde in June 1997 and used an Earth gravity assist in January 1998 to enable this low-cost mission. The spacecraft is currently on course for insertion into orbit about the asteroid 433 Eros in February 2000. The navigation for the cruise phase of the mission, even with its stringent requirements, is routine by comparison to the orbit phase of the mission. The navigation challenge for the orbit phase is to devise an adaptive orbit scenario that accounts for the crudely known asteroid physical parameters while maintaining required navigation accuracy. Improving the estimates of Eros' physical parameters such as spin state, shape and gravity potential of Eros. as the spacecraft approaches and is inserted into orbit about the asteroid is critical to mission success. Unlike a planetary orbiter, the very low gravity of the asteroid means that the spacecraft can easily escape Eros or crash into its surface with very little change in velocity. This places additional demand on navigation accuracy while also imposing a generally shorter response time than that usual for planetary orbit missions. This presentation details the response of the NEAR navigation team to these challenges in terms of design and execution of the orbit phase navigation. The approach chosen uses both DSN radio metric Doppler and range data and optical landmark tracking data for the normal estimation process. In addition, laser altimeter range is included in the navigation estimates whenever the spacecraft altitude is between about 30 km and 100 km.



# Challenges in NEAR Navigation

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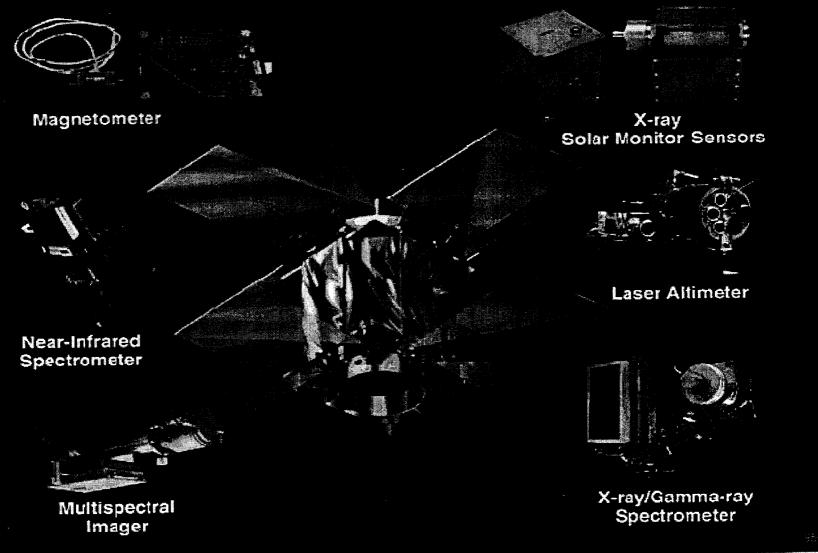
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California Institute of Technology
Pasadena, CA 91109

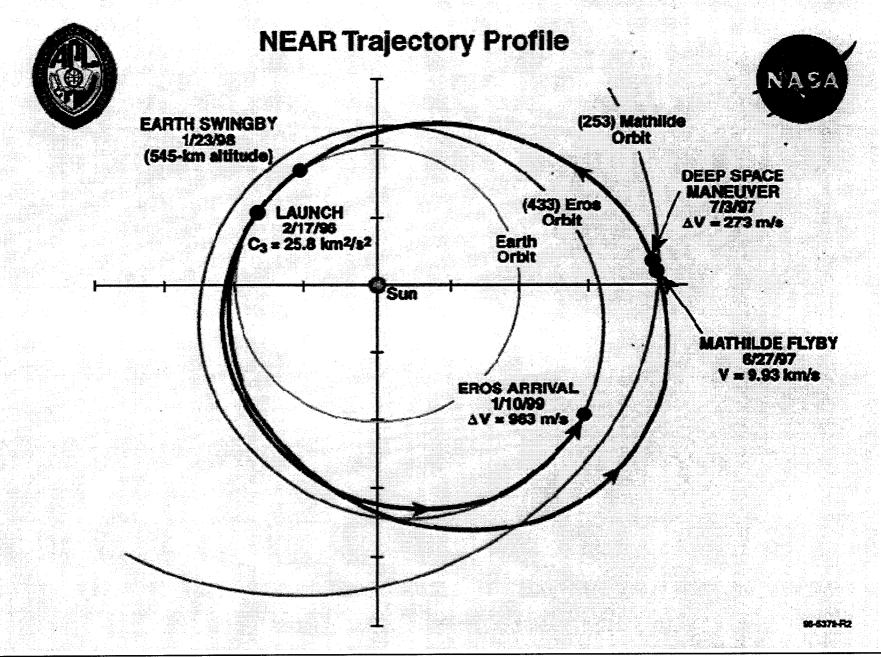




# NEAR SCIENCE PAYLOAD



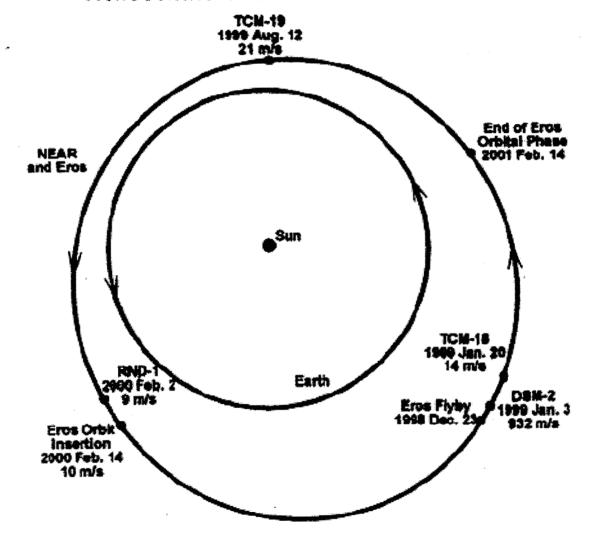






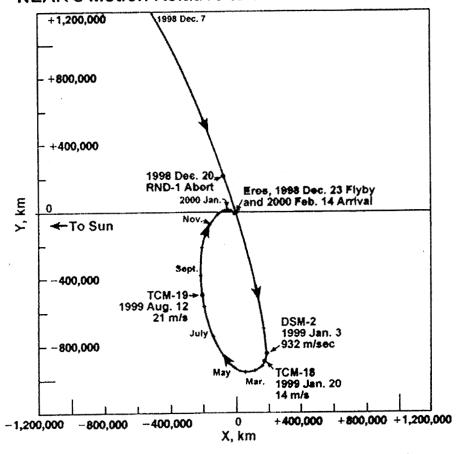
### Near Earth Asteroid Rendezvous

#### Hellocentric Orbits of NEAR and Eros





#### NEAR's Motion Relative to a Fixed Sun-Eros Line



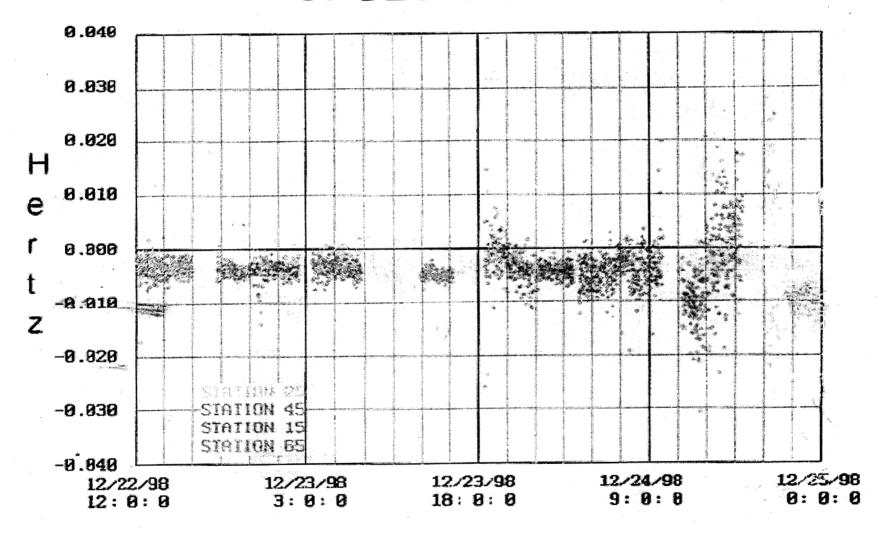
# **EROS IMAGE**

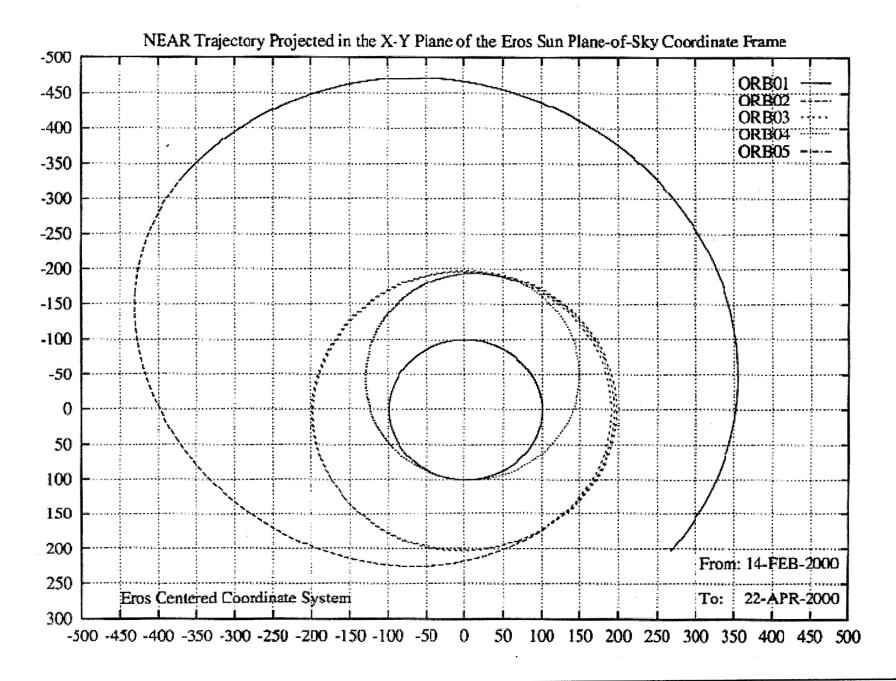
# Simulated Image

# Actual Image

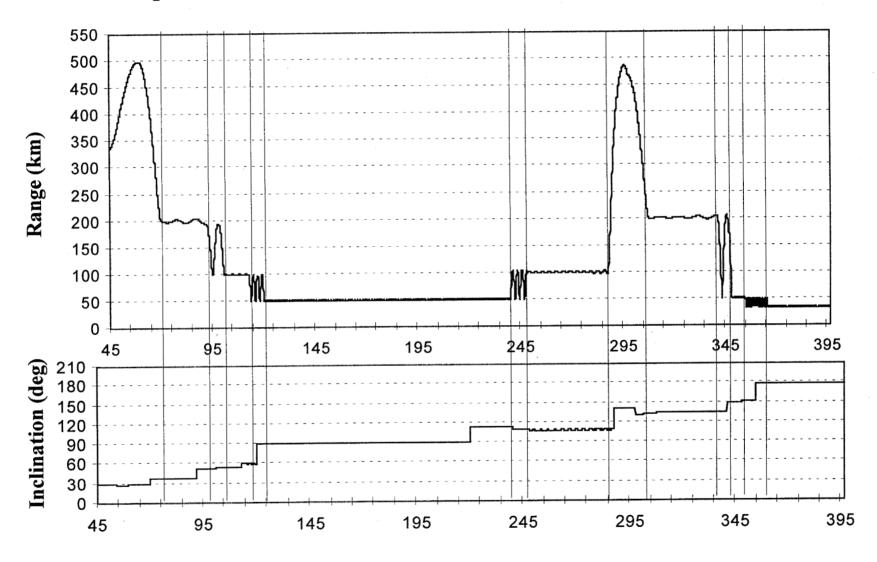


# NEAR EROS FLYBY DOPPLER RESIDUALS 60 SEC DATA





### **Spacecraft Trajectory Profile at Eros (4-7-99 version)**



Days since Jan 1, 2000

# NEAR Technical Review



# **Mapping Orbit Prediction Errors**









### NEAR Technical Review

#### Orbit Phase Initial Reconnaissance

#### Eros Physical Parameters

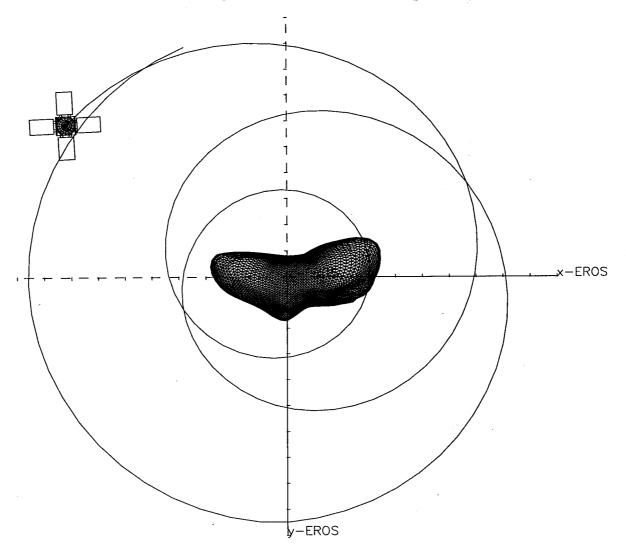
Parameter	Accuracy(1 sigma)	
	Apriori	Estenated
Attitude	10 deg	0.68 તેલ્યુ
Spin	1 deg/s	9.5 × 10 5 leg/s
Gravity $(\mu)$	100%	11.9577
Gravity $(J_2)$		$3.9 \times 10^{-2}$
Inertia Tensor $(I_{xx})$	1), ]	$7.6 \times 10^{-2}$
Landmark Location	41#1 m	130 m

† Data consisted of 3 days of Doppler and Optical Imaging of Landmarks

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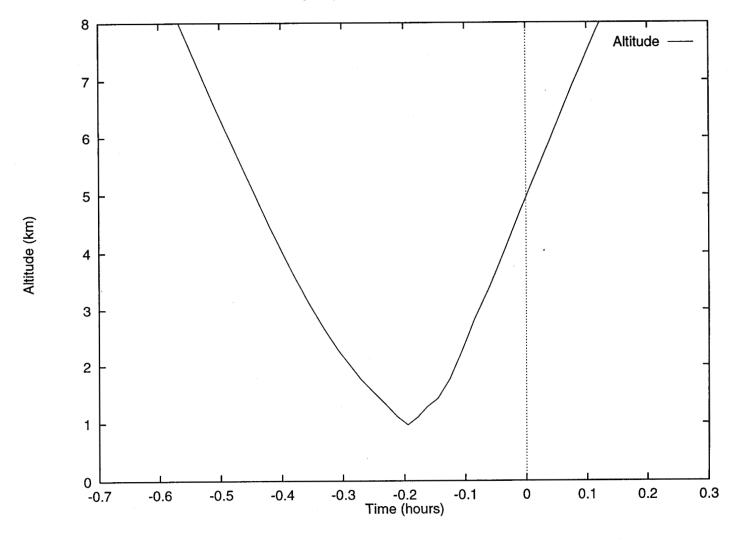
#### **JPL**

Body-fixed View of a 4th Quadrant (Trailing Edge) Close Flyby Orbit





# The Altitude Vs Time from Periapsis for 1st Close Flyby (59 X 16 km) Orbit





## Conclusion

- Navigation for NEAR uses radio metric and optical data types
  - Laser range also available below 100 km alt.
- Unlike planetary orbiter missions, navigation for NEAR depends on rapid estimates of asteroid physical parameters
  - Spin state, gravity field, shape





#### Eros Physical Parameters Reconstruction

#### Eros Physical Parameters

Paramete <b>r</b>	Accuracy(1 sigma)	
	Apriori	Estimate
Artifude		Pro cing
Spin		$5.6 \times 30^{-7} \deg/s$
Gravity $(\mu)$	1067	0.11%
Gravity $(J_2)$	man and a second	$1.2\times10^{-3}$
Inertia Tensor $(I_{xx})$	0.1	1.0 × 10-3
Landmark Location	-418() res	9.2 m

† Data consisted of 3 days of Doppler and Optical imaging of Landmarks



# The Shape Model of Eros Determined from NEAR's Flyby on Dec 23, 1998

